

Boundary Overlap Corrections for Segmented Line Transects

David Affleck¹, Timothy Gregoire¹, and Harry Valentine²

¹School of Forestry & Environmental Studies
Yale University

²U.S.D.A. Forest Service
Northeastern Research Station

2005 Western Mensurationists' Meeting

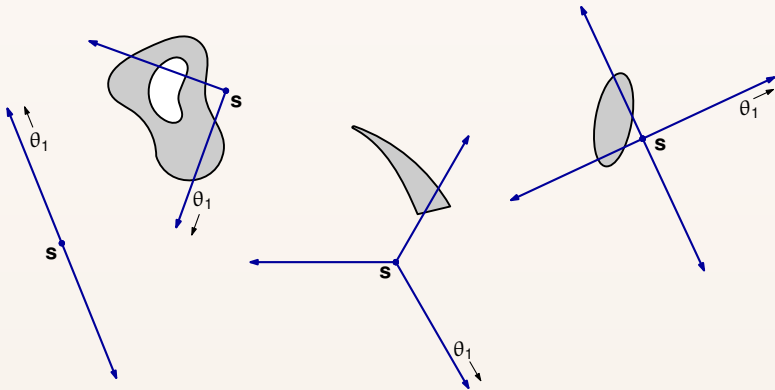
Outline

1. Line intersect sampling & segmented transects
2. Boundary overlap bias
3. Bias corrections
 - ▶ Symmetric radial transects
 - ▶ Asymmetric radial transects
 - ▶ Polygonal transects
4. Discussion

Segmented Transects

Radial

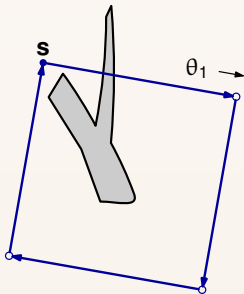
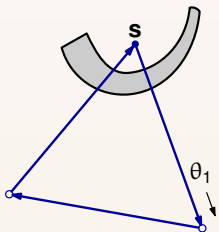
- ▶ $K \geq 1$ segments emanating from the sample point (\mathbf{s})



Segmented Transects

Polygonal

- ▶ $K > 2$ segments forming a closed figure at \mathbf{s}



Notation

Population:

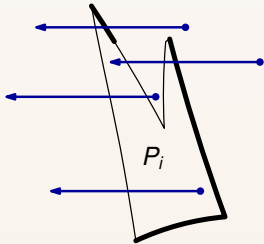
- ▶ N particles $\mathbf{P} = \{P_1, P_2, \dots, P_N\}$ on T
- ▶ Target parameter: $\tau = \sum_{i=1}^N y_i$

Sample Design:

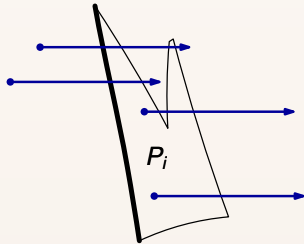
- ▶ \mathbf{s} randomly located on T
- ▶ $\boldsymbol{\theta} = [\theta_1, \theta_2, \dots, \theta_K]$ with θ_1 selected:
 1. Arbitrarily, in advance of sampling; or,
 2. Uniformly at random from $[0, 360^\circ]$

Selection Protocol

- ▶ t_{ik} is the number of times P_i is selected by segment k
- ▶ $t_{ik} = 1$ if segment k crosses the “leading edge”:



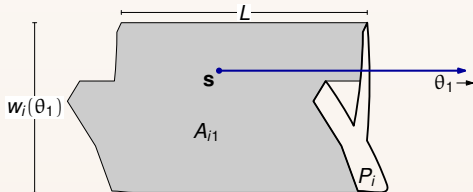
(a) $\theta_1 = 270^\circ$



(b) $\theta_1 = 90^\circ$

Inclusion Regions

- ▶ Given θ_k , A_{ik} is inclusion region of P_i corresponding to segment k :



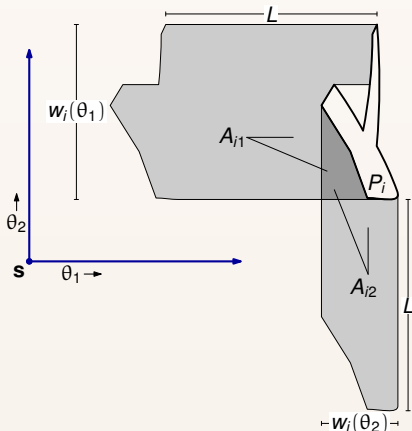
- ▶ $\Pr(t_{i1} = 1 | \theta_1) = \Pr(\mathbf{s} \in A_{i1} | \theta_1) = \frac{w_i(\theta_1)L}{T}$

Inclusion Regions

Radial Transects

$$\blacktriangleright t_{i\bullet} = \sum_{k=1}^K t_{ik}$$

$$\begin{aligned}\blacktriangleright E(t_{i\bullet}|\boldsymbol{\theta}) &= \sum_{k=1}^K \Pr(t_{ik} = 1|\theta_k) \\ &= K \frac{\bar{w}_i(\boldsymbol{\theta})L}{T}\end{aligned}$$



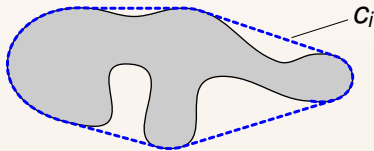
Estimation

Conditional on θ_1

- ▶ $\Pr(t_{ik} = 1 | \theta_k) = \frac{w_i(\theta_k) L}{T}$
- ▶ $E(t_{i\bullet} | \theta) = K \frac{\bar{w}_i(\theta) L}{T}$

Unconditional

- ▶ $\Pr(t_{ik} = 1) = \frac{c_i L}{\pi T}$
- ▶ $E(t_{i\bullet}) = K \frac{c_i L}{\pi T}$



$$E[w_i(\theta_1)] = \frac{c_i}{\pi}$$

Estimation

Conditional on θ_1

$$\blacktriangleright \Pr(t_{ik} = 1 | \theta_k) = \frac{w_i(\theta_k) L}{T}$$

$$\blacktriangleright E(t_{i\bullet} | \boldsymbol{\theta}) = K \frac{\bar{w}_i(\boldsymbol{\theta}) L}{T}$$

$$\blacktriangleright \hat{\tau}_c = \sum_{i=1}^N \frac{t_{i\bullet} y_i}{E(t_{i\bullet} | \boldsymbol{\theta})}$$

Unconditional

$$\blacktriangleright \Pr(t_{ik} = 1) = \frac{c_i L}{\pi T}$$

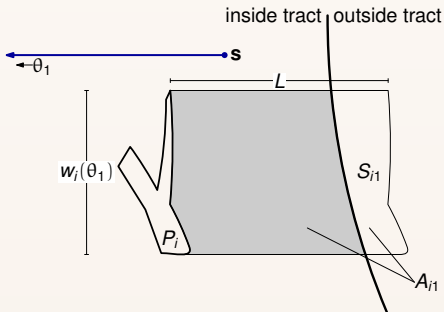
$$\blacktriangleright E(t_{i\bullet}) = K \frac{c_i L}{\pi T}$$

$$\blacktriangleright \hat{\tau}_u = \sum_{i=1}^N \frac{t_{i\bullet} y_i}{E(t_{i\bullet})}$$

Boundary Overlap

Radial Transects

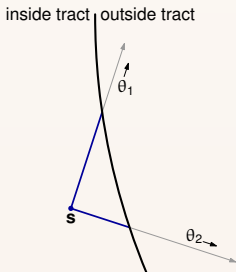
- ▶ For P_i near the edge, and some θ_1 :



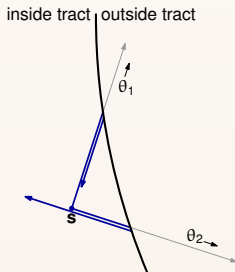
- ▶ $\Pr(t_{i1} = 1 | \theta_1) < \frac{w_i(\theta_1) L}{T} \implies \begin{cases} E(\hat{\tau}_c | \boldsymbol{\theta}) > \tau \\ E(\hat{\tau}_u) > \tau \end{cases}$

Reflection Method

Radial Transects



(a) Establish transect



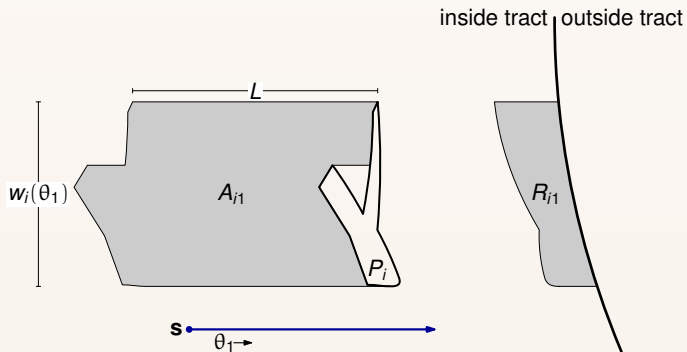
(b) Reflect each segment

$$t_{jk} = 0, 1, 2$$

- cf. Gregoire & Monkevich (1994) *Environ & Ecol Stat* 1: 219-226

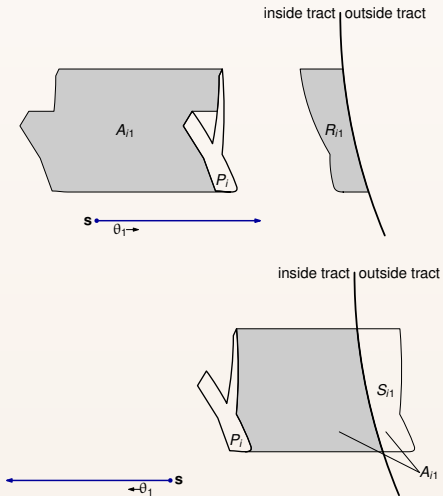
Reflection Method

Radial Transects



Reflection Method

Radial Transects



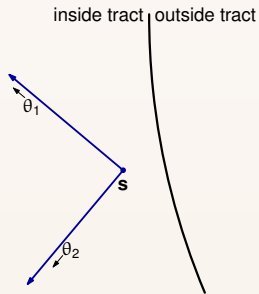
Reflection Method

Radial Transects

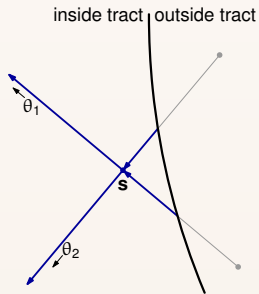
- ▶ $R_{j1} = S_{j2}$ if $\theta_2 = \theta_1 + 180^\circ$
- ▶ The reflection method is unbiased for:
 - ▶ Symmetric radial transects; *OR*
 - ▶ Randomly oriented radial transects
- ▶ The reflection method is *NOT* unbiased for:
 - ▶ asymmetric radial transects with fixed orientation

Walkback Method

Radial Transects



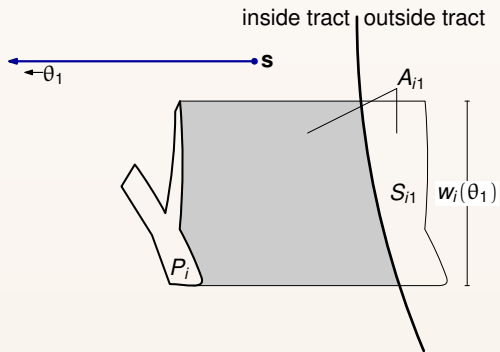
(a) Establish transect



(b) Extend each segment
 $t_{ik} = 0, 1$

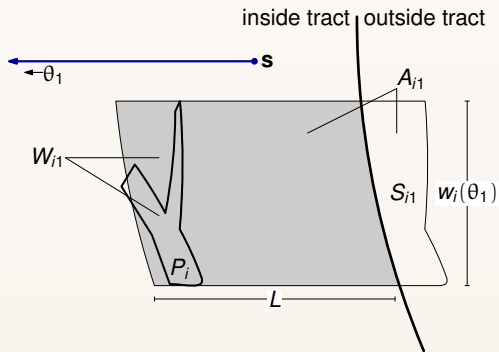
Walkback Method

Radial Transects



Walkback Method

Radial Transects



- ▶ $W_{i1} = S_{i1}$
- ▶ Walkback method is unbiased for any radial transect

Summary

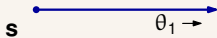
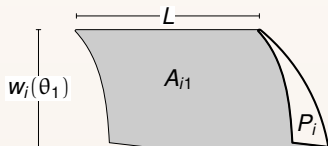
Radial Transects

To correct for boundary overlap bias:

1. Symmetric *OR* randomly oriented radial transects
 - ▶ Reflection method
2. Asymmetric radial transects with fixed orientation
 - ▶ Walkback method

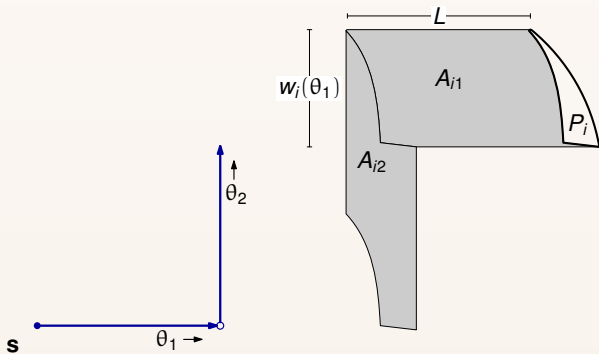
Inclusion Regions

Polygonal Transects



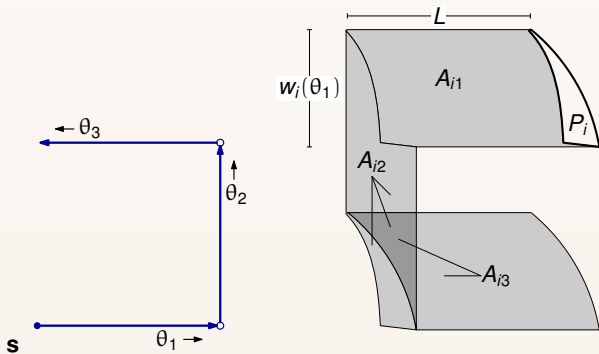
Inclusion Regions

Polygonal Transects



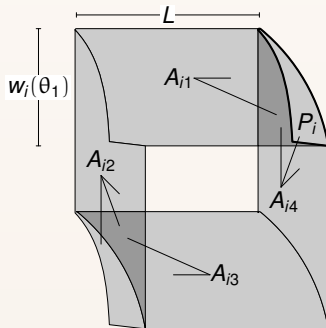
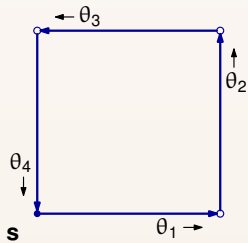
Inclusion Regions

Polygonal Transects



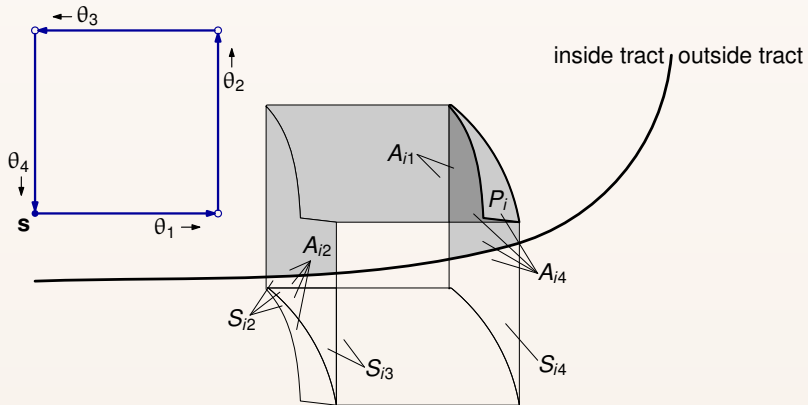
Inclusion Regions

Polygonal Transects



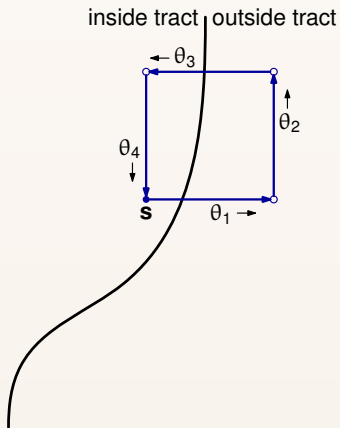
Boundary Overlap

Polygonal Transects



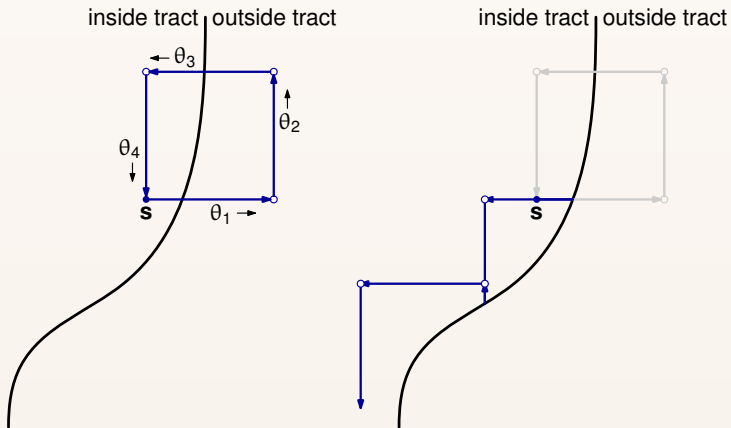
Reflection Method

Polygonal Transects



Reflection Method

Polygonal Transects



Summary

To correct for boundary overlap bias:

1. Symmetric *OR* randomly oriented radial transects
 - ▶ Reflection method
2. Asymmetric radial transects with fixed orientation
 - ▶ Walkback method
3. Polygonal transects with random orientation
 - ▶ Reflection method

Or sample outside the tract.

Acknowledgments

- ▶ **U.S.D.A. Forest Service**

Northeastern Research Station, RWU-4104

- ▶ **Yale University**

School of Forestry & Environmental Studies

Graduate School of Arts & Sciences Student Assembly